



US 20170278760A1

(19) **United States**

(12) **Patent Application Publication**
CHEN et al.

(10) **Pub. No.: US 2017/0278760 A1**

(43) **Pub. Date: Sep. 28, 2017**

(54) **INTERMEDIATE STRUCTURE FOR
TRANSFER, METHOD FOR PREPARING
MICRO-DEVICE FOR TRANSFER, AND
METHOD FOR PROCESSING ARRAY OF
SEMICONDUCTOR DEVICE**

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(21) Appl. No.: **15/080,607**

(22) Filed: **Mar. 25, 2016**

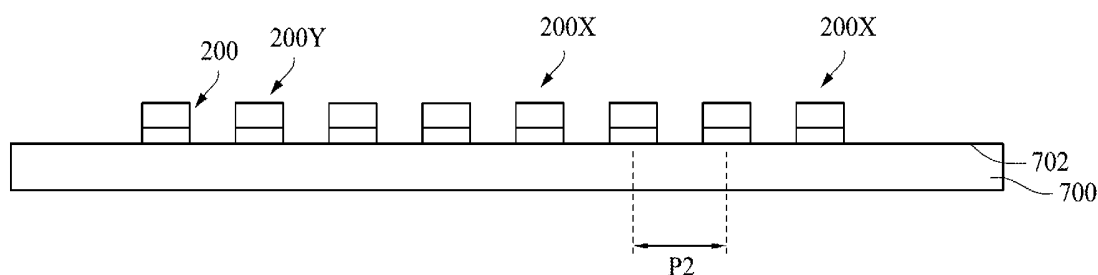
Publication Classification

(51) **Int. Cl.**
H01L 21/66 (2006.01)

(52) **U.S. Cl.**
CPC **H01L 22/22** (2013.01); **H01L 22/14**
(2013.01)

(57) **ABSTRACT**

A method for preparing a plurality of micro-devices for transfer includes temporarily bonding the micro-devices onto a carrier substrate; testing the micro-devices on the carrier substrate to determine if there is at least one first failed micro-device in the micro-devices; and removing the first failed micro-device from the carrier substrate.



100

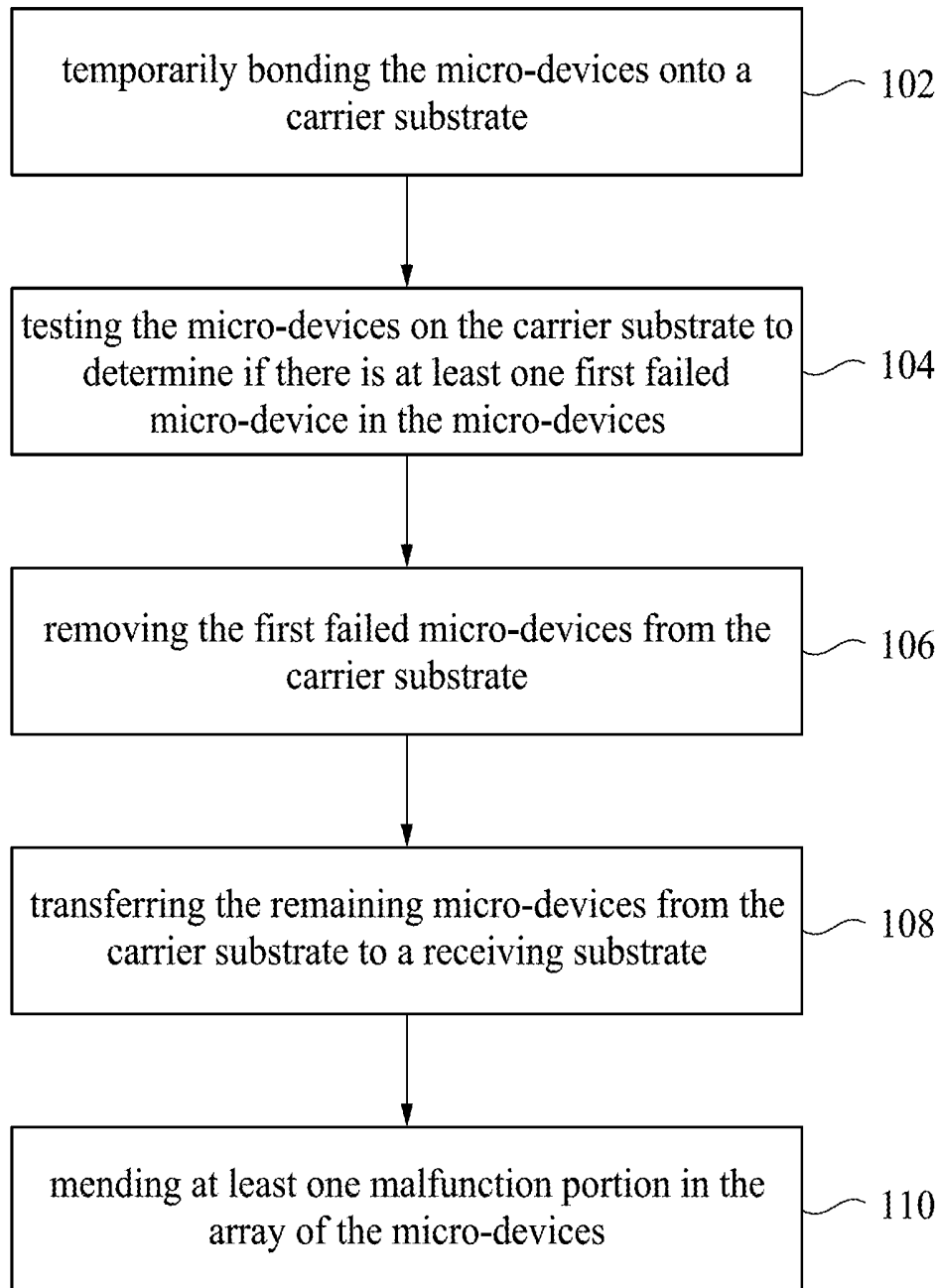


Fig. 1

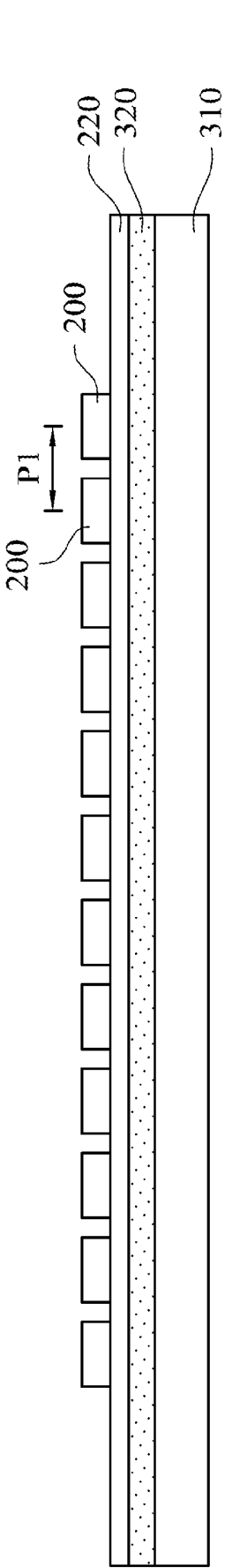


Fig. 2A

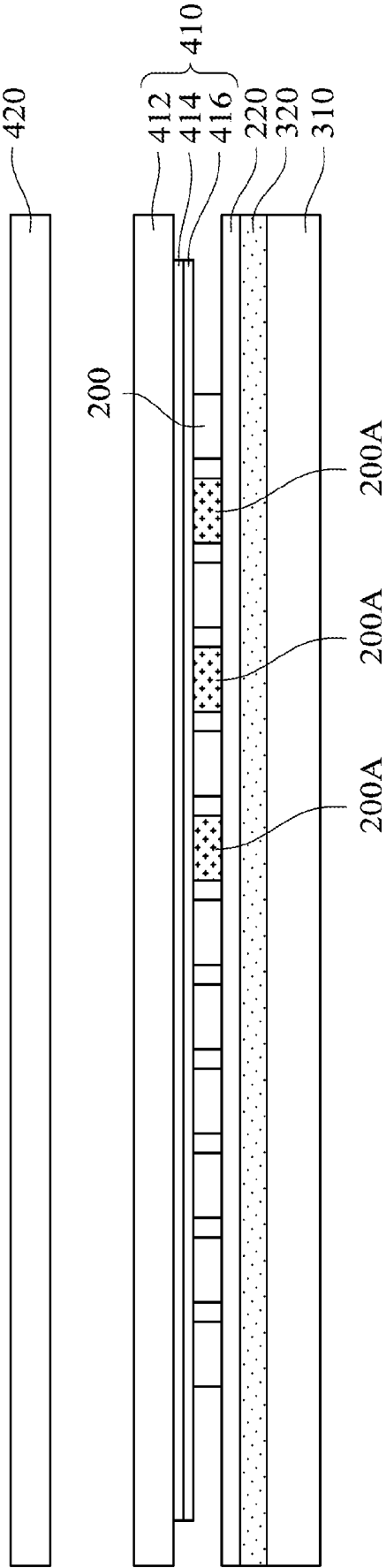


Fig. 2B

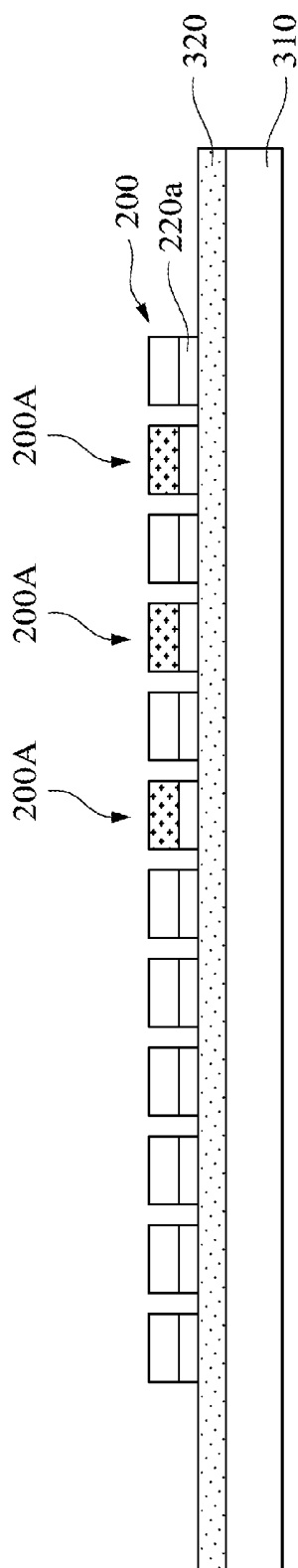


Fig. 2C

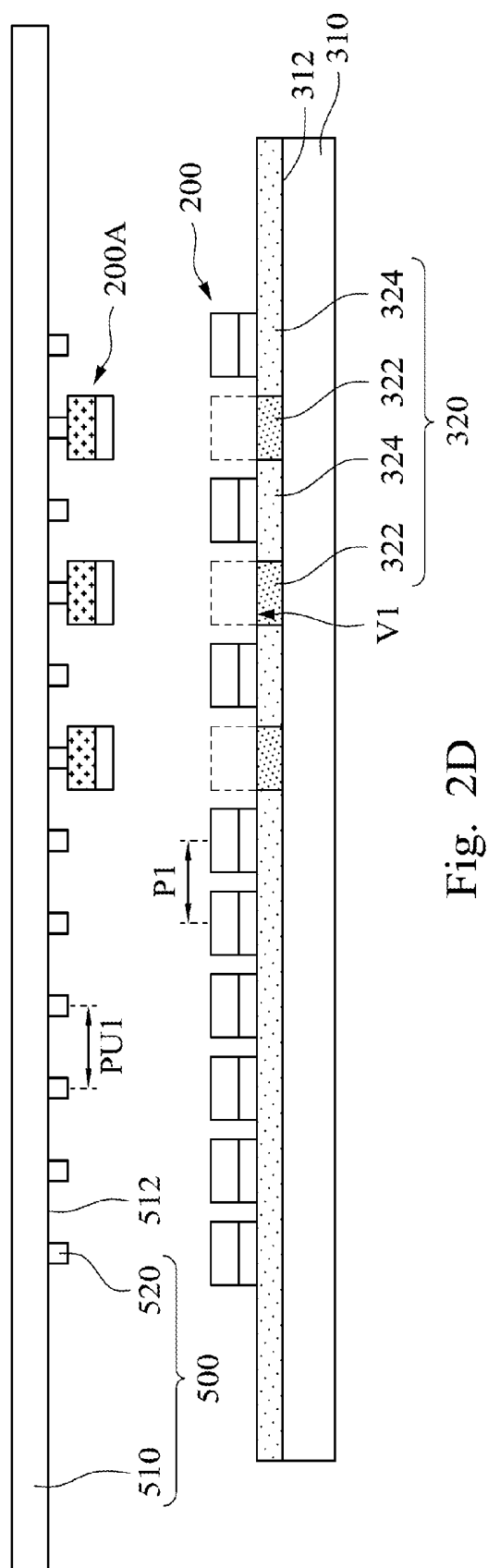


Fig. 2D

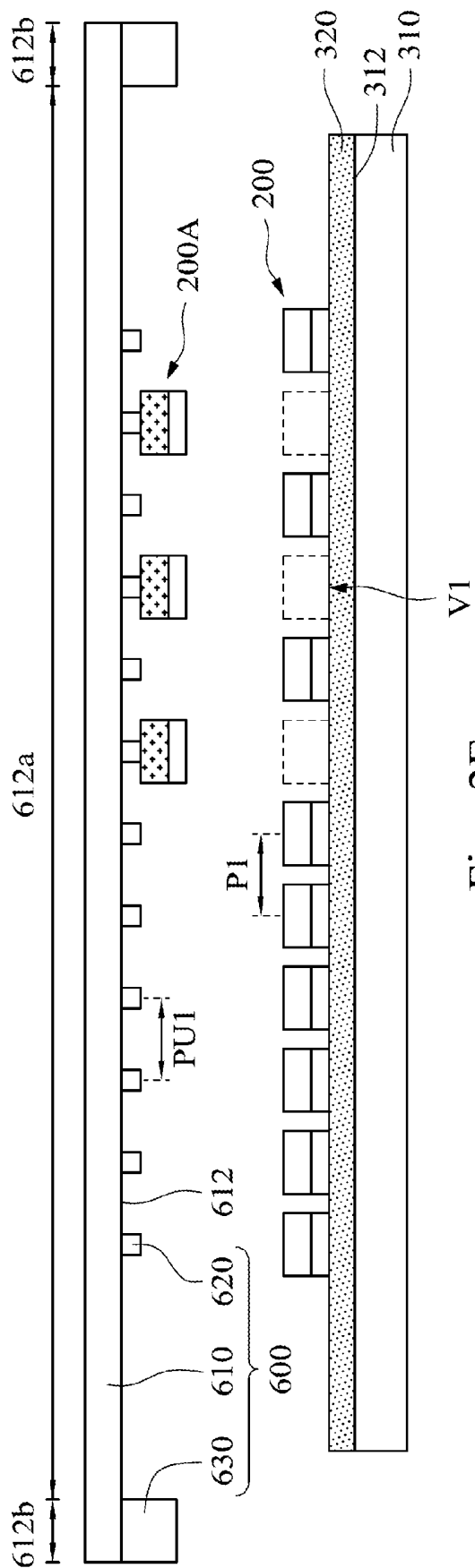


Fig. 2E

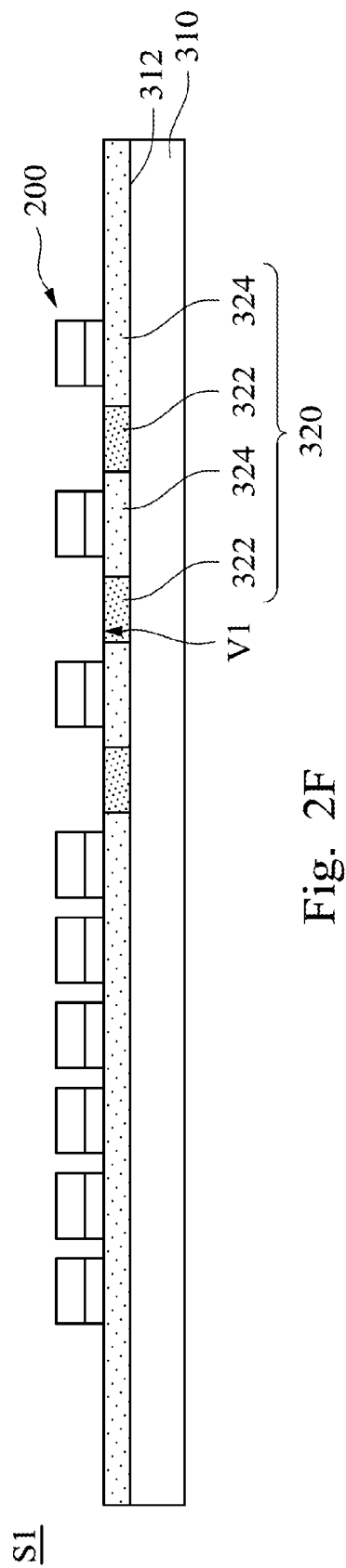


Fig. 2F

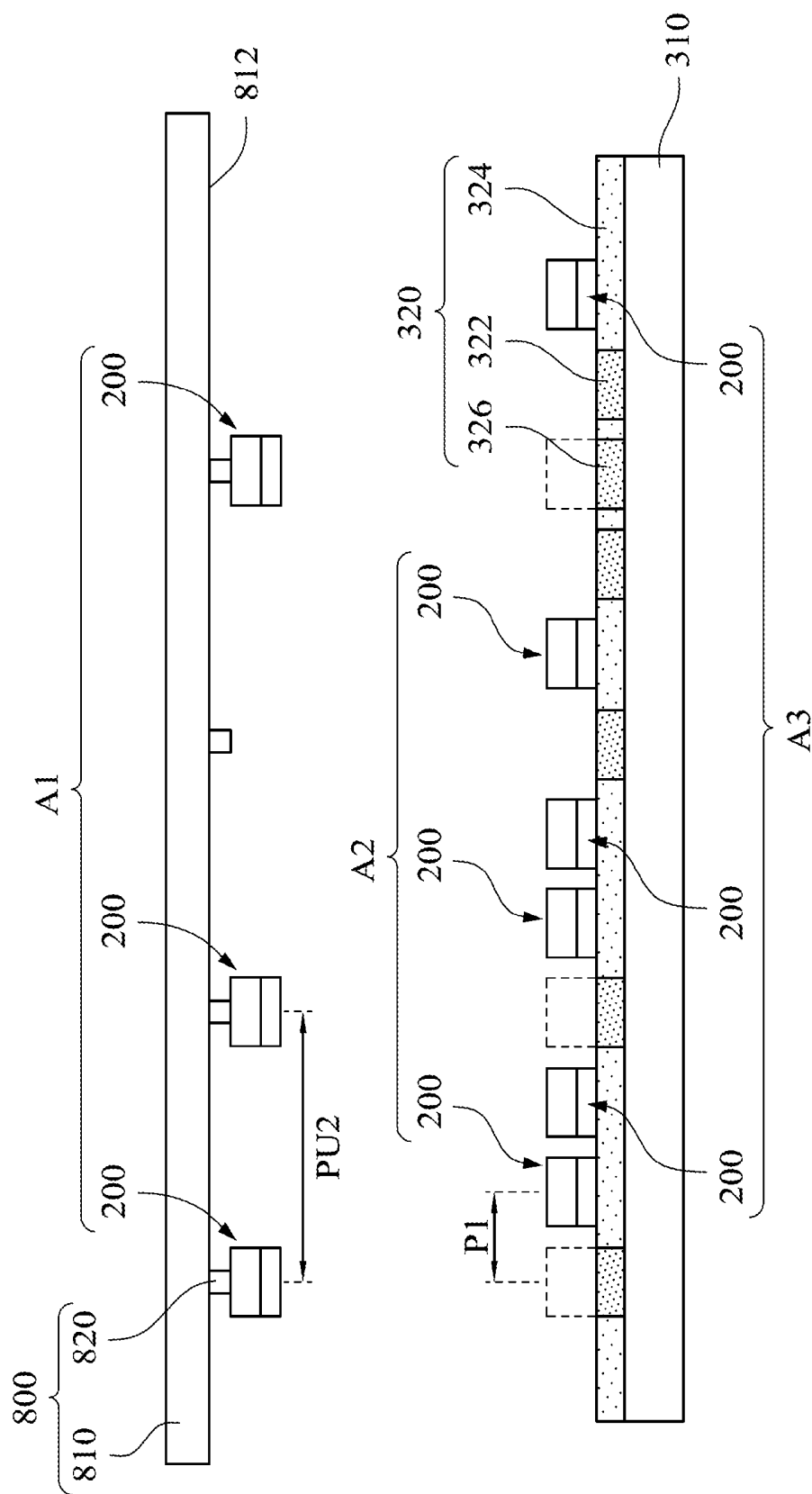


Fig. 2G

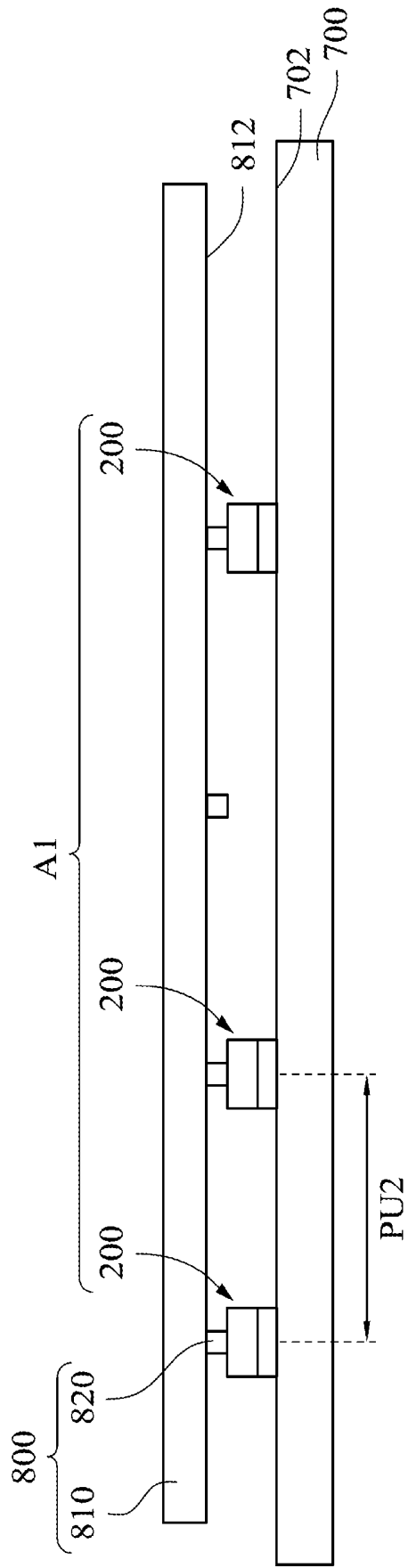


Fig. 2H

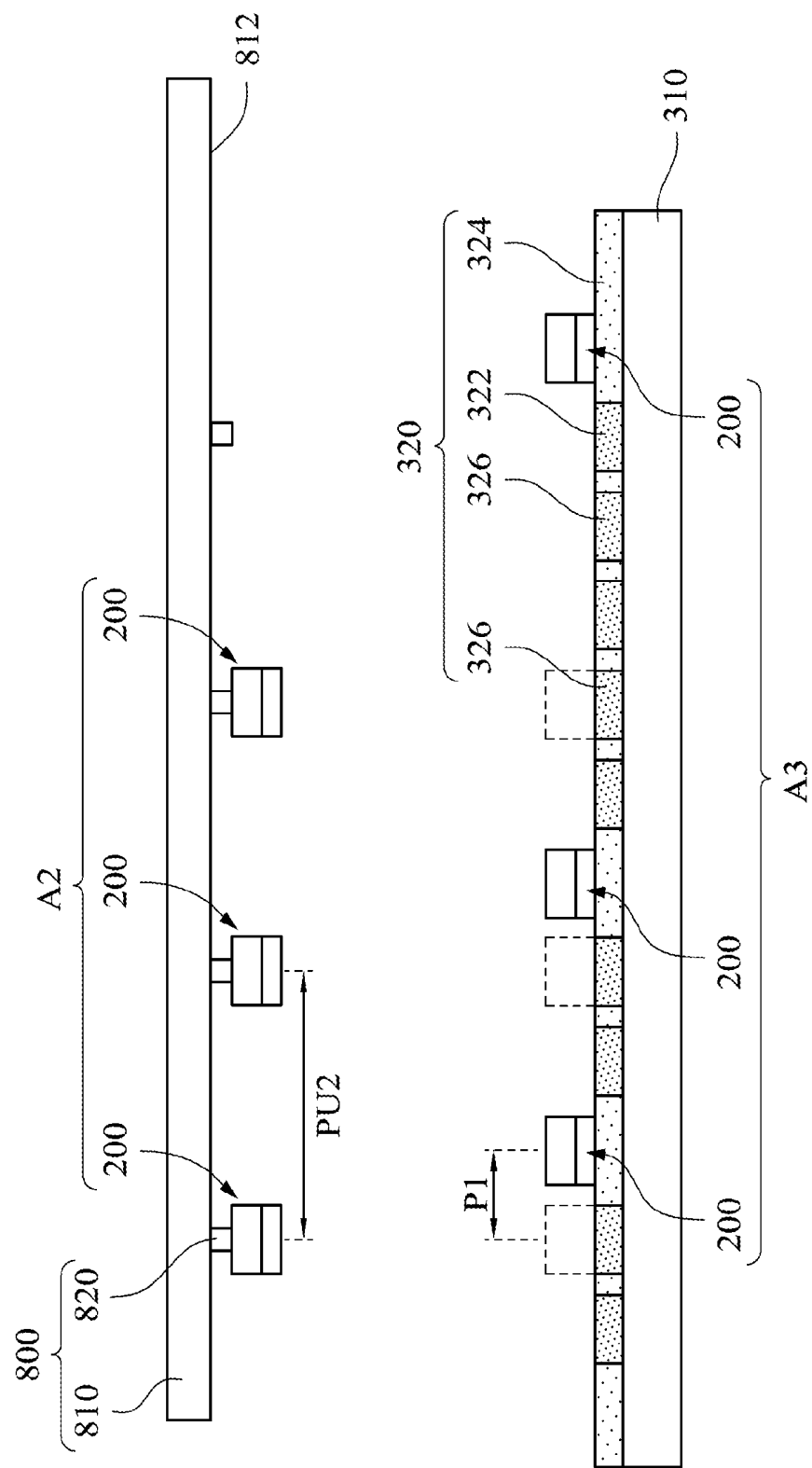


Fig. 2I

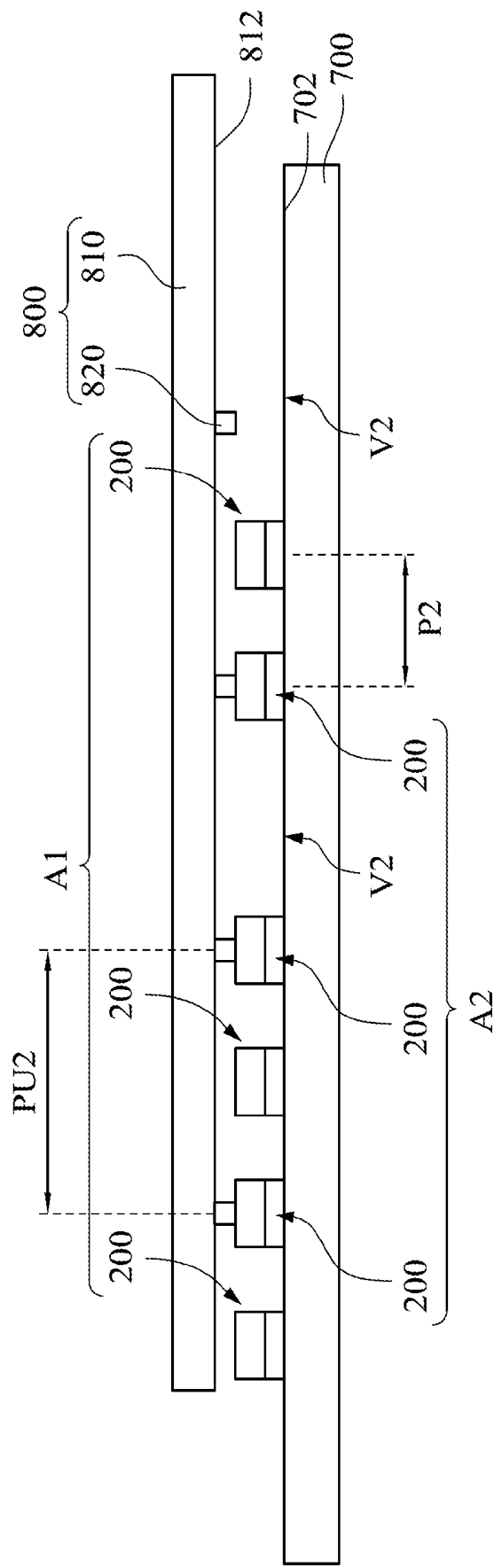


Fig. 2J

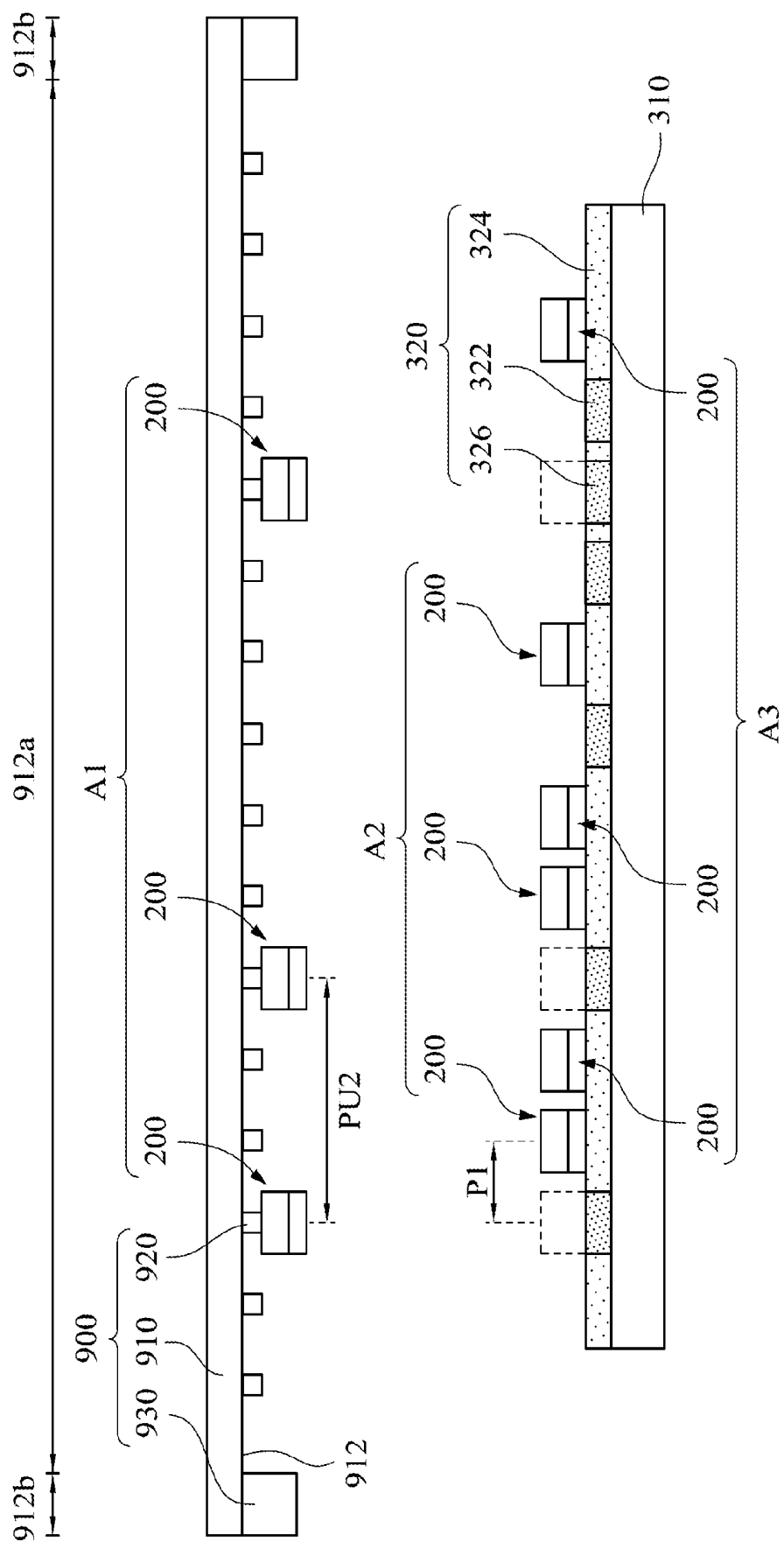


Fig. 2K

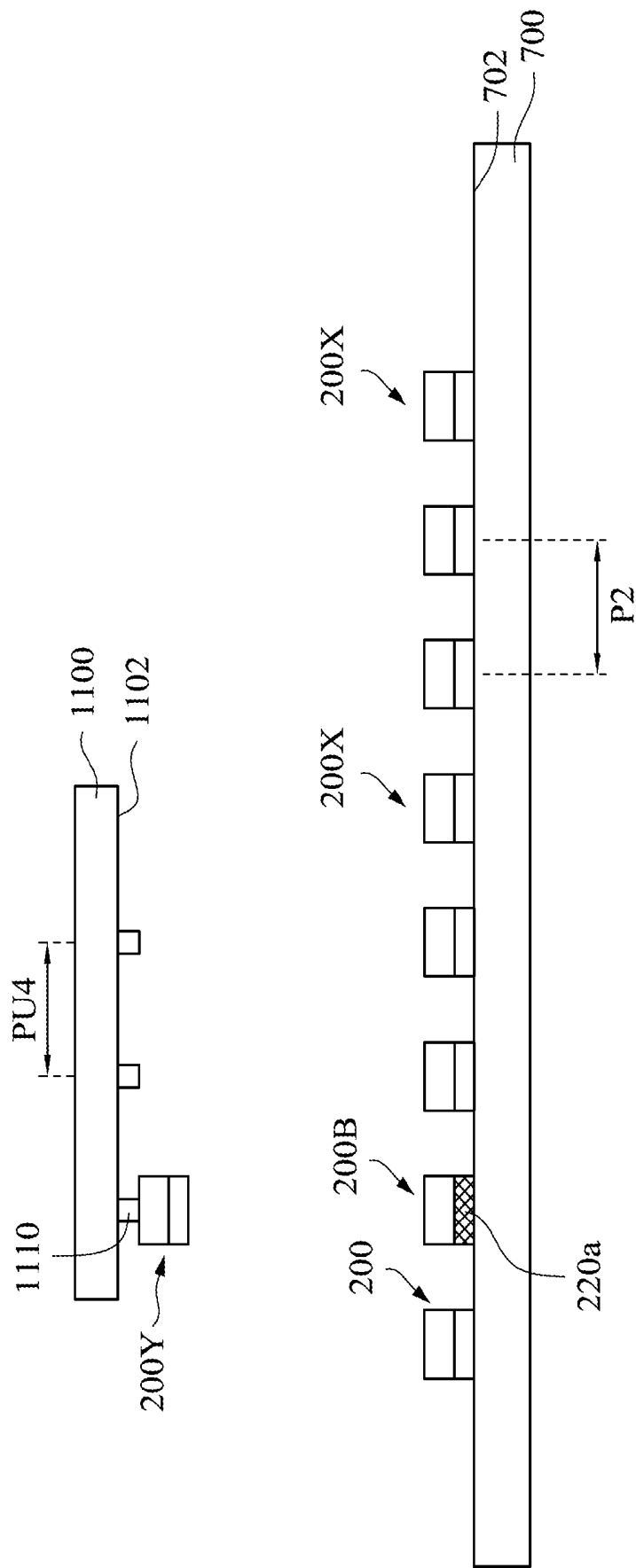


Fig. 2M

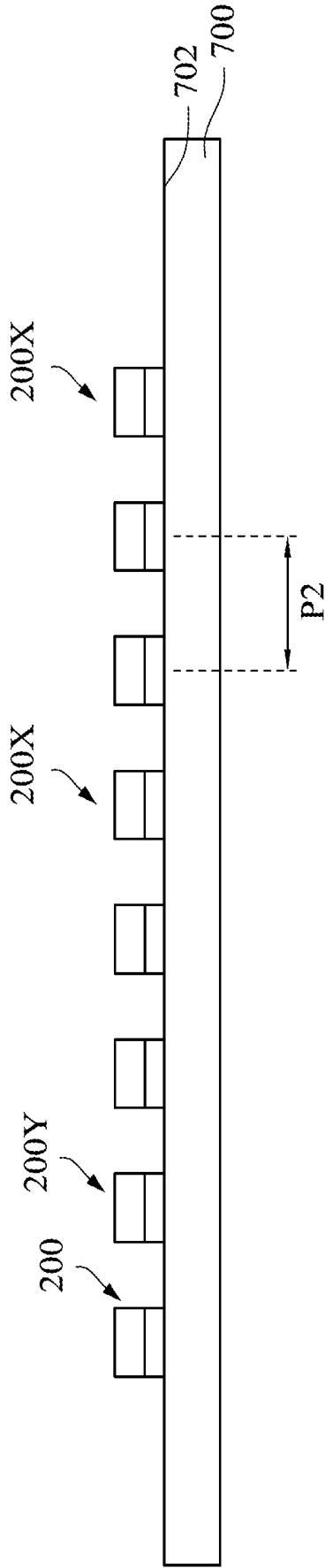


Fig. 2N

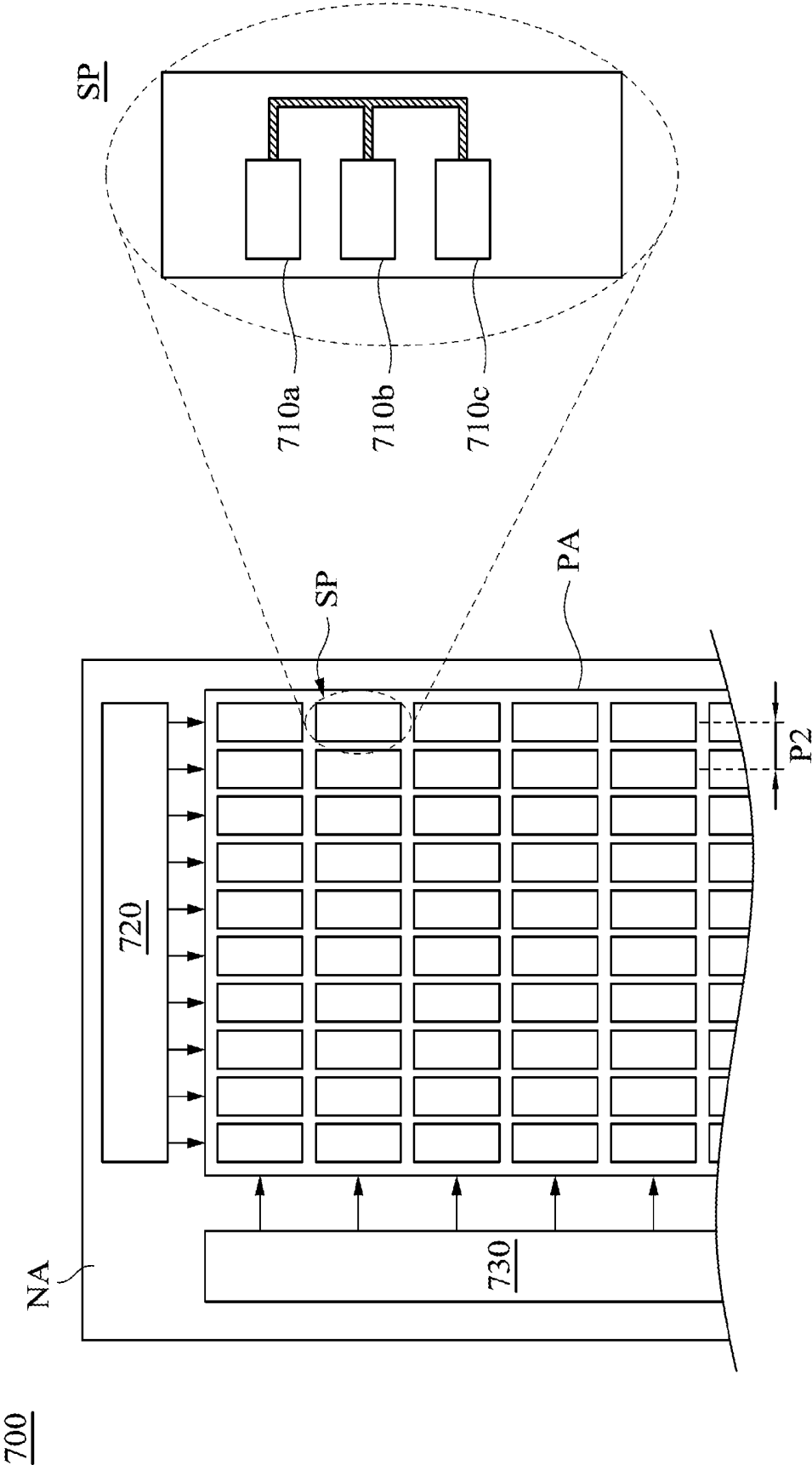


Fig. 3

INTERMEDIATE STRUCTURE FOR TRANSFER, METHOD FOR PREPARING MICRO-DEVICE FOR TRANSFER, AND METHOD FOR PROCESSING ARRAY OF SEMICONDUCTOR DEVICE

BACKGROUND

[0001] Technical Field

[0002] The present disclosure relates to active solid-state devices.

[0003] Description of Related Art

[0004] In the recent years, light-emitting diodes (LEDs) have become popular in general and commercial lighting applications. As being light sources, LEDs have many advantages including low energy consumption, long life-time, small size, and fast switching, and hence conventional illuminant technology, such as incandescent lamps, is gradually replaced by LEDs.

[0005] When light-emitting diodes are initially formed, a portion of the light-emitting diodes may be defective. When the light-emitting diodes are respectively transferred to pixels of a receiving substrate, the defective light-emitting diodes occupy spaces of the corresponding pixels but provide little performance for the illumination.

SUMMARY

[0006] According to some embodiments of this disclosure, a method for preparing a plurality of micro-devices for transfer is provided. The method includes temporarily bonding the micro-devices onto a carrier substrate; testing the micro-devices on the carrier substrate to determine if there is at least one first failed micro-device in the micro-devices; and removing the first failed micro-device from the carrier substrate.

[0007] According to some embodiments of this disclosure, an intermediate structure for transfer includes a carrier substrate, a plurality of tested semiconductor devices, and at least one temporary bonding layer. The tested semiconductor devices are present on the carrier substrate, in which the tested semiconductor devices pass at least one test, and there is no failed semiconductor device which does not pass the test on the carrier substrate. The temporary bonding layer is present between the tested semiconductor devices and the carrier substrate.

[0008] According to some embodiments of this disclosure, a method for processing an array of semiconductor devices is provided. The method includes disposing the array of semiconductor devices onto a receiving substrate, in which the array of semiconductor devices has at least one malfunctioning portion therein; and mending the malfunctioning portion in the array of semiconductor devices, wherein the mending comprises at least one of patching at least one void in the array of semiconductor devices with at least one patching semiconductor device when the malfunctioning portion comprises the void and repairing at least one failed semiconductor device in the array of semiconductor devices with at least one repairing semiconductor device when the malfunctioning portion comprises the failed semiconductor device.

[0009] It is to be understood that both the foregoing general description and the following detailed description are by examples, and are intended to provide further explanation of the disclosure as claimed.

BRIEF DESCRIPTION OF THE DRAWINGS

[0010] FIG. 1 is a flow chart of a method for transferring a plurality of micro-devices to a receiving substrate according to some embodiments of the present disclosure.

[0011] FIGS. 2A-2N are cross-sectional views of the method for transferring the micro-devices to the receiving substrate according to some embodiments of the present disclosure.

[0012] FIG. 3 is a top view of the receiving substrate according to some embodiments of the present disclosure.

DETAILED DESCRIPTION

[0013] Reference will now be made in detail to the present embodiments of the disclosure, examples of which are illustrated in the accompanying drawings. Wherever possible, the same reference numbers are used in the drawings and the description to refer to the same or like parts.

[0014] The terms “micro” device or “micro” LED (light-emitting diode) as used herein may refer to the descriptive size of certain devices in accordance with embodiments of the present disclosure. As used herein, the terms “micro” device or “micro” LED are meant to refer to the scale of 1 micrometer to 5 millimeters. However, it is to be appreciated that embodiments of the present disclosure are not necessarily so limited, and that certain aspects of the embodiments may be applicable to larger, and possibly smaller size scales.

[0015] It will be understood that when an element is referred to as being “on” another element, it can be directly on the other element or intervening elements may be present there between. In contrast, when an element is referred to as being “directly on” another element, there are no intervening elements present.

[0016] FIG. 1 is a flow chart of a method 100 for transferring a plurality of micro-devices to a receiving substrate according to some embodiments of the present disclosure. FIGS. 2A-2N are cross-sectional views of the method for transferring the micro-devices 200 to the receiving substrate 700 according to some embodiments of the present disclosure. It is understood that additional steps may be implemented before, during, or after the method 100, and some of the steps described may be replaced or eliminated for other embodiments of the method 100.

[0017] Referring to FIG. 1 and FIG. 2A, the method 100 begins at step 102 by temporarily bonding the micro-devices 200 onto a carrier substrate 310. The micro-devices 200 may be formed by epitaxially growing and etching a plurality of semiconductor layers. That is, the micro-devices 200 may include semiconductor devices, such as micro LEDs.

[0018] In some embodiments, a temporary bonding layer 320 may be initially disposed over the carrier substrate 310. A stack of semiconductor layers and a conductive layer 220 are attached to the temporary bonding layer 320, with the conductive layer 220 touching the temporary bonding layer 320. The semiconductor layers are patterned while the conductive layer 220 is not. The patterned semiconductor layers form the micro-devices 200 attached to the conductive layer 220. In some embodiments, the micro-devices 200 are arrayed on the carrier substrate 310, and adjacent micro-devices 200 on the carrier substrate 310 have a device pitch P1 therebetween.

[0019] In some embodiments of the present disclosure, the temporary bonding layer 320 bonds a combination of the micro-devices 200 and the conductive layer 220 to the

carrier substrate **310**. The temporary bonding layer **320** may be release adhesives, such as thermal release adhesives or UV (ultraviolet)-release adhesives. That is, the temporary bonding layer **320** is capable of being released by a variety of mechanisms, such as heating, UV exposure, or any combination thereof. The released temporary bonding layer provides little adhesion force against the conductive layer **220** and the carrier substrate **310**.

[0020] Referring to FIG. 1 and FIG. 2B, the method **100** proceeds to step **104** by testing the micro-devices **200** on the carrier substrate **310** to determine if there is at least one first failed micro-device **200A** in the micro-devices **200**. At least one of variety of methods for testing the micro-devices **200** is performed by utilizing a testing tool **410** to drive the micro-devices **200** and utilizing a photo sensor **420** to determine whether the micro-devices **200** are lighted.

[0021] Herein, the testing tool **410** may include a transparent substrate **412**, a transparent conductive layer **416**, and a transparent photoresist layer **414** disposed between the transparent substrate **412** and the conductive layer **416**. The transparent conductive layer **416** of the testing tool **410** is configured to touch the micro-devices **200**. To be specific, the testing tool **410** may touch the top surfaces of the micro-devices **200**. The configuration of the transparent photoresist layer **414** is optional and may be omitted in some embodiments. Through the configuration, the top surfaces of the micro-devices **200** are provided with a first potential. Meanwhile, the conductive layer **220** is provided with a second potential different from the first potential. Through the conductive layer **416** of the testing tool **410** and the conductive layer **220**, a potential difference may be formed, and the potential difference between the first potential and the second potential drives the micro-devices **200**.

[0022] The photo sensor **420**, e. g. a high resolution digital camera, may sense the lighting performance of the micro-devices **200**. If the micro-devices **200** exhibit no luminance or irregular luminance, the micro-devices **200** may be defective and designated as the first failed micro-devices **200A** (indicated with a cross-dot pattern). Furthermore, in some embodiments, an analyzer may be further adopted to analyze an I-V (current-voltage) curve or a leakage current of the micro-devices **200**. If the micro-devices **200** exhibit an irregular I-V curve or an abnormal leakage current, the micro-devices **200** may be defective and designated as the first failed micro-devices **200A**.

[0023] In some embodiments, for allowing the light emitted from the micro-devices **200** to be transmitted to the photo sensor **420** through the testing tool **410**, the conductive layer **416** of the testing tool **410** may be made of a transparent conductive material, such as indium tin oxide. The conductive layer **416** may or may not be patterned. Alternatively, the conductive layer **416** of the testing tool **410** may be nano-silver wires with a width in a range from about 10 nanometers to about 20 nanometers, such that most of the light emitted from the micro-devices **200** is not shielded by the nano-silver wires. Also, the transparent substrate **412** may be made of glass or acrylic that does not block light transmission.

[0024] In some embodiments, most of the micro-devices **200** are activated simultaneously, but it should not limit the various embodiments of the present disclosure. In some other embodiments, the testing tool **410** may touch one of the micro-devices **200** each time. For example, the testing

tool **410** may include at least one probe to touch at least one of the micro-devices **200** each time, and the micro-devices **200** are tested sequentially.

[0025] The methods for testing the micro-devices **200** are illustrated herein, and there may be other adequate methods for testing the micro-devices **200**. In still some other embodiments, the first failed micro-device **200A** may be determined by testing the photo-luminescence (PL) of the micro-devices **200**, instead of by activating the micro-devices **200**. Herein, the micro-devices **200** may be irradiated and scanned by a UV light (for example, UV lasers), such that the micro-devices **200** absorb the ultraviolet light and re-emit fluorescent light. The photo sensor **420** equipped with color filters may detect the fluorescent light. For example, for a red micro-LED, the photo sensor **420** is equipped with a red color filter for detecting the fluorescent light. If the micro-devices **200** exhibit no photo-luminescence or irregular photo-luminescence, the micro-devices **200** may be defective and designated as the first failed micro-devices **200A**.

[0026] Referring to FIG. 1 and FIG. 2C, after the testing, the conductive layer **220** (shown in FIG. 2B) may be patterned to form plural conductive pads **220a** attached to the bottoms of the micro-devices **200** respectively. Hereinafter, the micro-devices **200** each includes one of the conductive pads **220a**. In some other embodiments, the conductive layer **220** may be patterned before the testing in which the micro-devices **200** are not activated, such as the PL testing.

[0027] Referring to FIG. 1 and FIG. 2D, the method **100** proceeds to step **106** by removing the first failed micro-devices **200A** from the carrier substrate **310**. In some embodiments, the removing of the step **106** may include debonding and removing the first failed micro-devices **200A** from the carrier substrate **310** while leaving the other micro-devices **200** bonded on the carrier substrate **310**.

[0028] Herein, portions **322** of the temporary bonding layer **320** below the first failed micro-devices **200A** are locally released, such as being locally heated or exposed to UV light, and portions **324** of the temporary bonding layer **320** below the normal micro-devices **200** are not being released. The released portions **322** are indicated with a dense dotted pattern, while the portions **324** are indicated with a sparse dotted pattern. Therefore, the first failed micro-devices **200A** are initially debonded from the carrier substrate **310**, and the normal micro-devices **200** are still bonded to the carrier substrate **310**.

[0029] After the temporary bonding layer **320** is locally released, a transfer head **500** exerts a uniform attracting force on all of the micro devices **200** including the first failed micro-devices **200A**. The released portions **322** of the temporary bonding layer **320** provide little adhesion force against the first failed micro-devices **200A**. The attracting force of the transfer head **500** is greater than the adhesion force between the released portions **322** and the first failed micro-devices **200A**, such that the first failed micro-devices **200A** are picked by the transfer head **500**, and at least one void **V1** is left in the array of the micro-devices **200**. In addition, the adhesion force between the portions **324** of the temporary bonding layer **320** and the normal micro devices **200** is maintained and is greater than the attracting force between the normal micro devices **200** and the transfer head

500. Therefore, the normal micro devices **200** stay on the carrier substrate **310** while the first failed micro-devices **200A** are picked up.

[0030] The transfer head **500** includes at least one electrostatic chuck, using such as but not limited to the attraction of opposite charges to pick up the first failed micro-devices **200A**. The transfer head **500** includes a body **510**, plural picking units **520**, and a connection circuit (not shown). The body **510** has a working surface **512** where the picking units **520** are arranged. In some embodiments, the connection circuit may include a plurality of conductive lines, which are thin and not shown in FIG. 2D. The conductive lines are disposed on the working surface **512** and connected to all the picking units **520** for simultaneously activating the picking units **520**. The connection circuit (such as the conductive lines) has a height lower than the height of the picking units **520**, and therefore does not physically obstruct the picking units **520** from approaching the first failed micro-devices **200A**.

[0031] In some other embodiments, instead of electrostatic chucking, the transfer head **500** may use adhesive chucking or a combination of the adhesive chucking and the electrostatic chucking. An adhesion force between the transfer head **500** and the micro-devices **200** is provided by, for example, adhesive protrusions, and the adhesion force between the transfer head **500** and the micro-devices **200** is designed to be greater than the adhesion force between the released portions **322** of the temporary bonding layer **320** and the failed micro-devices **200A**, so that the transfer head **500** can pick up the failed micro-devices **200A** by the adhesion force between the transfer head **500** and the micro-devices **200**. In still some other embodiments, the picking units **520** can operate with principles of vacuum grippers or mechanical grippers, or the picking units **520** can be any element applicable to pick up the first failed micro-devices **200A**.

[0032] In the present embodiments, the transfer head **500** exerts a uniform attracting force on all of the micro devices **200**, and the first failed micro-devices **200A** are debonded and removed from the carrier substrate **310** by the transfer head **500** at one time. In some other embodiments, the micro-devices **200** may be grouped, the transfer head **500** exerts uniform attracting forces on the groups of the micro devices **200** sequentially, and the first failed micro-devices **200A** in the groups may be debonded and removed from the carrier substrate **310** by the transfer head **500** sequentially. For example, one of the first failed micro-devices **200A** may be debonded and removed from the carrier substrate **310** by transfer head **500** initially, and then the another of the first failed micro-devices **200A** may be debonded and removed from the carrier substrate **310** by transfer head **500**.

[0033] The utilization of the transfer head **500** and the locally released temporary bonding layer **320** should not limit the addressable removal of the first failed micro-devices **200A**. Referring to FIG. 2E, instead of the operation shown in FIG. 2D, the removing of the step **106** may include debonding the micro-devices **200** from the carrier substrate **310** and addressably removing the first failed micro-devices **200A** from the carrier substrate **310**. Herein, as being indicated with a dense dotted pattern, the entire temporary bonding layer **320** is substantially released, such as being uniformly heated or UV exposed, and an addressable transfer head **600** is utilized for addressably picking the first failed micro-devices **200A**.

[0034] The addressable transfer head **600** includes a body **610**, plural picking units **620**, and an addressable peripheral driving circuit **630**. The body **610** has a working surface **612** having a picking region **612a** and at least one circuit region **612b** disposed at at least one side of the picking region **612a**. The picking units **620** are arranged in the picking region **612a**. The addressable peripheral driving circuit **630** is disposed at least in the circuit region **612b**.

[0035] In some embodiments, the addressable transfer head **600** may use electrostatic chucking. As the picking units **520** of the non-addressable transfer head **500** (shown in FIG. 2D), the picking units **620** may be electrostatic grippers, using such as but not limited to the attraction of opposite charges to pick up the first failed micro devices **200A**. In some other embodiments, the picking units **620** can operate with principles of vacuum grippers, adhesive grippers, or mechanical grippers, or the picking units **620** can be any element applicable to pick up the first failed micro devices **200A**.

[0036] The addressable peripheral driving circuit **630** may include at least one integrated circuit disposed in the circuit region **612b** and conductive lines (not shown) disposed in both the circuit region **612b** and the picking region **612a** for electrically connecting the integrated circuit and the picking units **620**. Though the configuration, the addressable peripheral driving circuit **630** is capable of addressably activating the picking units **620**.

[0037] As shown in FIG. 2E, in some embodiments, the picking region **612a** is configured to be larger than or equal to a supporting surface **312** of the carrier substrate **310**, and therefore the picking units **620** is capable of approaching the first failed micro devices **200A**.

[0038] In the embodiments of FIG. 2D and FIG. 2E, adjacent picking units **520** of the non-addressable transfer head **500** or adjacent picking units **620** of the addressable transfer head **600** have a pitch PU1 therebetween. Though the pitch PU1 is substantially the same as the pitch P1, it should not limit various embodiments of the present disclosure. In some other embodiments, the pitch PU1 may be an integral multiple of the pitch P1, such as $N \times P1$, in which N is an integer. In furtherance of the embodiments, a portion of the first failed micro-devices **200A** may be removed by the transfer head **500** or the addressable transfer head **600** at the previous step, and another portion of the first failed micro-devices **200A** may be removed by said transfer head **500** or said addressable transfer head **600** at the later step. In some embodiments, the first failed micro-devices **200A** may be grouped into N groups, and the step of removing the first failed micro-devices **200A** may be repeated N times.

[0039] Referring to FIG. 2F, after the removing, an intermediate structure S1 for transfer is provided. The intermediate structure S1 includes a carrier substrate **310**, plural tested micro-devices **200**, and at least one temporary bonding layer **320**. The tested micro-devices **200** are present on the carrier substrate **310**, in which the tested micro-devices **200** pass at least one test, and there is no failed micro-device which does not pass the test on the carrier substrate **310**. In some embodiments, the tested micro-devices **200** are arranged in an array, while at least one void V1 is present in the array. The temporary bonding layer **320** may bond the tested micro-devices **200** onto the carrier substrate **310**. Alternatively, in some embodiments, the temporary bonding layer **320** may be entirely released.

[0040] Referring to FIG. 1 and FIGS. 2G-2J, the method 100 proceeds to step 108 by transferring the remaining micro-devices 200 from the carrier substrate 310 to a receiving substrate 700 after the removing. The transferring is performed by at least one non-addressable transfer head 800 capable of non-addressably picking the remaining micro-devices 200. In some embodiments, a debanding process may be performed for locally releasing the temporary bonding layer 320, such that the non-addressable transfer head 800 is capable of picking the remaining micro-devices 200.

[0041] The non-addressable transfer head 800 may use electrostatic chucking, adhesive chucking, or any combination thereof. In some embodiments, the non-addressable transfer head 800 may have a similar structure as the transfer head 500 (shown in FIG. 2D). As the configuration of the transfer head 500 (shown in FIG. 2D), the non-addressable transfer head 800 includes a body 810, plural picking units 820, and a connection circuit (not shown) electrically connected to all the picking units 820 for simultaneously activating the picking units 820.

[0042] In some embodiments, the receiving substrate 700 has an array of pixels corresponding to the array of micro-devices 200. Reference is made to FIG. 2G, FIG. 2H, and FIG. 3. FIG. 3 is a top view of the receiving substrate 700 according to some embodiments of the present disclosure. In some embodiments, the receiving substrate 700 may support a pixel area PA and at least one non-pixel area NA disposed at at least one side of the pixel area PA. The pixel area PA includes an array of sub-pixels SP arranged in a matrix. Adjacent sub-pixels SP have a pitch P2 therebetween. The non-pixel area NA includes at least one data line driving circuit 720 and at least one scan line driving circuit 730 thereon. The data line driving circuit 720 and the scan line driving circuit 730 are electrically connected to every sub-pixel SP.

[0043] As shown in FIG. 3, in some embodiments, each of the sub-pixels SP includes plural electrodes 710a, 710b, and 710c, which are connected. When the array of the micro-devices 200 is deposited onto the receiving substrate 700, the micro-devices 200 are located on the sub-pixels SP respectively, and each micro-device 200 is connected to one of the electrodes 710a, 710b, and 710c of each sub-pixel SP.

[0044] Reference is made back to FIGS. 2G-2J. As shown in FIG. 2G, the micro-devices 200 are divided into a plurality of groups, for example, the group A1, the group A2, and the group A3. The groups A1-A3 of the micro-devices 200 have substantially the same pitch, which is substantially the same as the pitch PU2 of the picking units 820 of the non-addressable transfer head 800. Therefore, in the transferring, the non-addressable transfer head 800 may sequentially transfer some of the groups A1-A3 to the receiving substrate 700 (shown in FIG. 2H).

[0045] To be specific, as shown in FIG. 2G and FIG. 2H, the group A1 of the micro-devices 200 is gripped by the non-addressable transfer head 800 and released onto the receiving substrate 700. Herein, the temporary bonding layer 320 below the group A1 of the micro-devices 200 are released and indicated as the released portions 326, while the temporary bonding layer 320 below the groups A2 and A3 of the micro-devices 200 are not released and indicated as the unreleased portions 324. Through the configuration, the groups A2 and A3 of the micro-devices 200 are kept to be bonded on the carrier substrate 310 by the portions 324 of

the temporary bonding layer 320, while the group A1 of the micro-devices 200 is picked up and transferred by the non-addressable transfer head 800.

[0046] As shown in FIG. 2I and FIG. 2J, the group A2 of the micro-devices 200 is gripped by the non-addressable transfer head 800 and released onto the receiving substrate 700, while the group A1 of the micro-devices 200 is previously disposed on the receiving substrate 700. Herein, the temporary bonding layer 320 below the group A2 of the micro-devices 200 is released and indicated as the released portions 326. Through these steps, the group A2 of the micro-devices 200 is transferred onto the receiving substrate 700. In some embodiments of the present embodiments, since the first failed micro-devices 200A are removed, there may be at least one void V2 in the array of the micro-devices 200 on the receiving substrate 700.

[0047] Though the groups A1 and A2 of the micro-devices 200 are alternatively arranged, it should not limit various embodiments of the present disclosure. In some other embodiments, the groups A1 and A2 of the micro-devices 200 may have a different arrangement on the receiving substrate 700.

[0048] As shown in FIG. 2G, adjacent picking units 820 of the non-addressable transfer head 800 include the pitch PU2 therebetween, and the pitch PU2 is an integral multiple of the pitch P1. Through the configuration, the non-addressable transfer head 800 is capable of picking the groups A1 and A2 of the micro-devices 200 on the carrier substrate 310 at different stages. On the other hand, as shown in FIG. 2J, adjacent micro-devices 200 on the receiving substrate 700 has the pitch P2 therebetween, which is the same as the pitch P2 of the sub-pixels SP (shown in FIG. 3), and the pitch PU2 is an integral multiple of the pitch P2. In other words, referring to FIGS. 2G and 2J, the pitch PU2 is configured to be a common multiple of the pitch P1 and the pitch P2.

[0049] In some embodiments, the micro-devices 200 are of different types, such as red-light micro LEDs, green-light micro LEDs, and blue-light micro LEDs. The micro-devices 200 on different carrier substrates may have the same pitch P1. When the micro-devices 200 of different types are transferred from different carrier substrates but to the same-receiving substrate 700, the pitch PU2 of the picking units 820 is configured to be a common multiple of the pitch P1, the pitch P2, and the number of the types of the micro-devices 200.

[0050] Referring to FIG. 2H, in some embodiments, the body 810 of the non-addressable transfer head 800 has a working surface 812 where the picking units 820 are arranged. Herein, the working surface 812 is smaller than the supporting surface 702 of the receiving substrate 700. The working surface 812 may be larger than or equal to the pixel area PA of the receiving substrate 700 (shown in FIG. 3). In some other embodiments, the working surface 812 may be larger than or equal to the supporting surface 702 of the receiving substrate 700.

[0051] Reference is made to FIG. 2K, in some other embodiments, the transferring is performed by at least one transfer head 900 capable of addressably picking at least one of the remaining micro-devices 200, instead of the non-addressable transfer head 800 shown in FIGS. 2G-2J. Reference is made to FIG. 2F and FIG. 2K, the transferring may include addressably transferring at least one group of the remaining micro-devices 200 from the carrier substrate 310 to the receiving substrate 700 and addressably transferring

at least another group of the remaining micro-devices **200** from the carrier substrate **310** to the receiving substrate **700**. FIG. 2K shows the initial step of the transferring, in which the group A1 of the micro-devices **200** is gripped from the carrier substrate **300** and the groups A2 and A3 of the micro-devices **200** are left on the carrier substrate **310**.

[0052] In some embodiments, since the transfer head **900** is capable of addressably picking the remaining micro-devices **200**, the entire temporary bonding layer **320** of the intermediate structure S1 (shown in FIG. 2F) may be substantially released by, for example, uniformly heating or UV exposure.

[0053] In some embodiments, the transfer head **900** may have a similar structure as the addressable transfer head **600** (shown in FIG. 2E). The addressable transfer head **900** includes a body **910**, plural picking units **920**, and an addressable peripheral driving circuit **930**. The body **910** has a working surface **912** having a picking region **912a** and at least one circuit region **912b** disposed at at least one side of the picking region **912a**. The picking units **920** are arranged in the picking region **912a**. The addressable peripheral driving circuit **930** is disposed at least in the circuit region **912b**. Herein, the work surface **912** of the body **910** may be greater than the supporting surface **702** of the receiving substrate **700** (shown in FIG. 2H and FIG. 2J). To be specific, the picking region **912a** is greater than the supporting surface **702** of the receiving substrate **700** (shown in FIG. 2H and FIG. 2J), such that the transfer head **900** may approach the receiving substrate **700** (shown in FIG. 2H and FIG. 2J). The detail structure of the transfer head **900** is similar to the configuration of the addressable transfer head **600** (shown in FIG. 2E), and therefore not repeated herein.

[0054] Reference is made back to FIG. 2J. In some embodiments, after the transferring, there may be at least one malfunctioning portion in the array of the micro-devices **200** on the receiving substrate **700**, in which the malfunctioning portion may result from the voids V2 or some of the micro-devices **200** which are not successfully bonded to the electrodes of the receiving substrate **700**.

[0055] Referring to FIG. 1 and FIGS. 2L-2M, the method **100** proceeds to step **110** by mending at least one malfunctioning portion in the array of the micro-devices **200**. The location of the voids V2 on the receiving substrate **700** may be inferred from the positions of the first failed micro-devices **200A** (shown in FIG. 2C). In some embodiments, during or after the transferring, the micro-devices **200** on the receiving substrate **700** are tested to determine if there is at least one second failed micro-device **200B** on the receiving substrate **700**, and the location of the second failed micro-device **200B** is obtained thereto. The second failed micro-device **200B** is the micro-device **200** that fails to be properly bonded to one of the electrodes **710a**, **710b**, and **710c** (shown in FIG. 3). To be specific, the contact pad **220a** of the second failed micro-device **200B** is not successfully electrically connected to one of the electrodes **710a**, **710b**, and **710c** (shown in FIG. 3) of the receiving substrate **700** and is indicated with a cross-hatch pattern.

[0056] Herein, the mending for the void V2 and the second failed micro-device **200B** may be performed respectively in FIG. 2L and FIG. 2M. To be specific, the mending includes at least one of patching the voids V2 in the array of micro-devices **200** with at least one patching micro-devices **200X** when the malfunctioning portion includes the voids V2 and repairing at least one second failed micro-device

200B in the array of the micro-devices **200** with at least one repairing micro-devices **200Y** when the malfunctioning portion includes the second failed micro-device **200B**. In some embodiments, a plurality of malfunctioning portions are mended by plural steps, and the mending includes mending at least one of the malfunctioning portions initially and mending at least another of the malfunctioning portions subsequently. The mending for the voids V2 and the second failed micro-device **200B** may be performed by electrostatic chucking, adhesive chucking, or any combination thereof.

[0057] Referring to FIG. 2L, the voids V2 on the receiving substrate **700** are patched with at least one patching micro-device **200X**. Herein, a transfer head **1000** having a similar structure as the non-addressable transfer head **800** (shown in FIG. 2G) may be adopted for the patching, but the work surface **1002** of the transfer head **1000** may be smaller than that of the non-addressable transfer head **800** (shown in FIG. 2G). To be specific, since the transfer head **1000** is used for patching a certain region in the array of micro-devices **200** but not an entire region in the array of micro-devices **200**, the working surface **1002** of the transfer head **1000** may be smaller than the supporting surface **702** of the receiving substrate **700**. Furthermore, the working surface **1002** of the transfer head **1000** may be smaller than the pixel area PA of the receiving substrate **700** (shown in FIG. 3).

[0058] In some embodiments, the transfer head **1000** may patch the voids V2 by plural times, in which the transfer head **1000** releases one or more patching micro-devices **200X** on the receiving substrate **700** each time.

[0059] In some embodiments, the first failed micro-devices **200A** may be in a regular pattern, and therefore the voids V2 may be present in the regular pattern. In some embodiments, the patching is performed by at least one transfer head **1000** having a patterned picking surface corresponding to the regular pattern of the voids V2, such that the void V2 may be patched with the transfer head **1000** by non-addressable picking the patching micro-device **200X**. For example, the picking units **1010** of the transfer head **1000** has a pitch PU3 therebetween, and the pitch PU3 is substantially the same as the distance between two of the voids V2.

[0060] In some embodiments, the patching micro-devices **200X** may be micro-devices disposed on another carrier substrate (not shown). Alternatively, in some other embodiments, the micro-devices **200** disposed on the carrier substrate **310** (shown in FIG. 2F) may not be totally transferred to the receiving substrate **700**, and the patching micro-devices **200X** may be a portion of the micro-devices **200** left on the carrier substrate **310** (shown in FIG. 2I), such as the groups A3 of the micro-devices **200**.

[0061] In some embodiments, the pitch PU3 of the picking units **1010** is a common multiple of the pitch P2 and the pitch of the patching micro-devices **200X** on the corresponding carrier substrate (not shown). In some other embodiments, the micro-devices **200** are of different types, such as red-light micro LEDs, green-light micro LEDs, and blue-light micro LEDs. The pitch PU3 of the picking units **1010** is a common multiple of the pitch P2, the number of the types of the micro-devices **200**, and the pitch of the patching micro-devices **200X** on the corresponding carrier substrate (not shown).

[0062] In some embodiments, before or after the patching, the micro-devices **200** on the receiving substrate **700** are tested to determine if there is at least one second failed

micro-device **200B** on the receiving substrate **700**. Reference is made to both FIG. 2M and FIG. 3. In some embodiments, a testing tool (such as the testing tool **410** in FIG. 2B) and a photo sensor (such as the photo sensor **420** in FIG. 2B) may be utilized. The pixel circuit (including the electrodes **710a**, **710b**, and **710c**, the data line driving circuit **720**, and the scan line driving circuit **730**) on the receiving substrate **700** and the testing tool drive the micro-devices **200** with a potential difference, such that the photo sensor may determine whether the micro-devices **200** are lighted. As the step **104** illustrated in FIG. 1 and FIG. 2B, if the micro-devices **200** exhibit no luminance, irregular luminance, an irregular I-V curve, or an abnormal leakage current, the micro-devices **200** may be defective and designated as the second failed micro-devices **200B**.

[0063] Referring to FIG. 2M and FIG. 3, the second failed micro-device **200B** on the receiving substrate **700** is repaired with at least one repairing micro-devices **200Y** by the transfer head **1100**.

[0064] Through the plural electrodes **710a**, **710b**, and **710c** of each of the sub-pixels SP, if there is a second failed micro-device **200B** on the electrodes **710a**, the second failed micro-device **200B** may not be removed from the electrodes **710a**. Because there are the electrodes **710b** and **710c** within the sub-pixel SP (shown in FIG. 3), the repairing micro-device **200Y** can be bonded to the electrode **710b** or **710c**. As a result, the damage caused by removal of the second failed micro-device **200B** can be avoided, and the yield rate of manufacturing the light-emitting diode display device is improved.

[0065] Herein, a transfer head **1100** have a similar structure as the non-addressable transfer head **800** (shown in FIG. 2G) may be adopted for the repairing. To be specific, the working surface **1102** of the transfer head **1100** may be smaller than the pixel area PA of the receiving substrate **700** (shown in FIG. 3).

[0066] Though it is not shown in FIG. 2M, in some embodiments, there may be a plurality of second failed micro-devices **200B** in a regular pattern. Therefore, the repairing may be performed by the transfer head **1100** having a patterned picking surface corresponding to the second failed micro-device **200B**, such that the second failed micro-device **200B** may be repaired with the transfer head **1100** by non-addressable picking the repairing micro-device **200Y**. To be specific, in some embodiments, the picking units **1110** of the transfer head **1100** may have a pitch PU4 therebetween, and the pitch PU4 of the picking units **1110** may be substantially the same as the distance between two of the second failed micro-device **200B**, such that the picking units **1110** may release the repairing micro-devices **200Y** to the sub-pixels SP (shown in FIG. 3) where the second failed micro-device **200B** are disposed.

[0067] In some embodiments, the transfer head **1100** may repair a plurality of second failed micro-devices **200B** by plural times, in which the transfer head **1100** releases one or more repairing micro-devices **200Y** on the receiving substrate **700** each time.

[0068] In some embodiments, the repairing micro-devices **200Y** may be micro-devices disposed on another carrier substrate (not shown). Alternatively, in some other embodiments, the repairing micro-devices **200Y** may be a portion of the micro-devices **200** disposed on the carrier substrate **310** (shown in FIG. 2I), such as the groups A3 of the micro-devices **200**.

[0069] In some embodiments, the pitch PU4 of the picking units **1110** is a common multiple of the pitch P2 and the pitch of the repairing micro-devices **200Y** on the corresponding carrier substrate (not shown). In some other embodiments, the micro-devices **200** are of different types, such as red-light micro LEDs, green-light micro LEDs, and blue-light micro LEDs. The pitch PU4 of the picking units **1110** is a common multiple of the pitch P2, the number of types of the micro-devices **200**, and the pitch of the repairing micro-devices **200Y** on the corresponding carrier substrate (not shown).

[0070] The transfer head **1000** in FIG. 2L and the transfer head **1100** in FIG. 2M are illustrated as non-addressable transfer heads which may use electrostatic chucking, adhesive chucking, or any combination thereof. The non-addressable transfer heads may have the patterned picking surface corresponding to the regular pattern of the malfunctioning portions. However, in some embodiments, the transfer head **1000** and the transfer head **1100** may be addressable transfer heads while the addressable driving circuits may be formed on the backside of the body, such that the addressable driving circuits does not obstruct the picking units **1010** or the picking units **1110** from approaching the micro devices **200** on the receiving substrate **700**.

[0071] After the repairing, the micro-devices on the receiving substrate **700** are tested to determine if each of the sub-pixels SP (shown in FIG. 3) has at least one normal micro-device thereon. After the testing, a data acquisition module (not illustrated) can collect the test result and the position information of the failed micro-devices of each of the sub-pixels SP (shown in FIG. 3). Thereafter, if most or all of the sub-pixels SP (i. g. more than 99.8% of the sub-pixels SP) are tested to have normal micro-devices, the test is passed. On the other hand, if at least a predetermined percentage of the sub-pixels SP (e.g. at least 0.2% of the sub-pixels SP) are tested to have no normal micro-devices, the repairing process is repeated. It should be understood that, the defect rate of performing the step **110** could be set to meet the production control.

[0072] Referring to FIG. 2N, an apparatus having an array of micro devices with few or no malfunctioning portion is obtained. To be specific, the apparatus has the patching micro devices **200X**, the repairing micro device **200Y**, and the micro devices **200** which have fine semiconductor layers (which indicate the micro devices **200** at least pass the test shown in FIG. 2B). In some embodiments, the patching micro devices **200X**, the repairing micro device **200Y**, and the micro devices **200** may have substantially the same structure.

[0073] In some embodiments of the present disclosure, the micro-devices on a carrier substrate are tested, and the defective micro-devices are removed from the carrier substrate. When the micro-devices are respectively transferred to pixels of a receiving substrate, the defective micro-devices are neither transferred to the receiving substrate nor occupying spaces of corresponding pixels of the receiving substrate. Voids on the receiving substrate are patched with patching micro-devices, and the failed micro-devices, which are unsuccessfully attached to the receiving substrate, are repaired with repairing micro-devices.

[0074] Although the present disclosure has been described in considerable detail with reference to certain embodiments thereof, other embodiments are possible. Therefore, the

spirit and scope of the appended claims should not be limited to the description of the embodiments contained herein.

[0075] It will be apparent to those skilled in the art that various modifications and variations can be made to the structure of the present disclosure without departing from the scope or spirit of the disclosure. In view of the foregoing, it is intended that the present disclosure cover modifications and variations of this disclosure provided they fall within the scope of the following claims.

What is claimed is:

1. A method for preparing a plurality of micro-devices for transfer, the method comprising:

temporarily bonding the micro-devices onto a carrier substrate;

testing the micro-devices on the carrier substrate to determine if there is at least one first failed micro-device in the micro-devices; and

removing the first failed micro-device from the carrier substrate.

2. The method of claim 1, wherein the removing comprises:

debonding the micro-devices from the carrier substrate; and

addressably removing the first failed micro-device from the carrier substrate.

3. The method of claim 1, wherein the removing comprises:

debonding the first failed micro-device from the carrier substrate while leaving the other micro-device bonded on the carrier substrate; and

removing the debonded first failed micro-device.

4. The method of claim 1, further comprising:

transferring the remaining micro-devices from the carrier substrate to a receiving substrate after the removing.

5. The method of claim 4, wherein the transferring is performed by at least one transfer head capable of addressably picking at least one of the remaining micro-devices.

6. The method of claim 4, wherein the transferring is performed by at least one transfer head capable of non-addressably picking the remaining micro-devices.

7. The method of claim 4, wherein the transferring is performed by electrostatic chucking, adhesive chucking, or any combination thereof.

8. The method of claim 4, wherein the transferring comprises:

addressably transferring at least one of the remaining micro-devices from the carrier substrate to the receiving substrate; and

addressably transferring at least another of the remaining micro-devices from the carrier substrate to the receiving substrate.

9. The method of claim 4, further comprising:

acquiring at least one location of at least one micro-device void on the receiving substrate; and

patching the micro-device void on the receiving substrate with at least one patching micro-device.

10. The method of claim 9, further comprising:

storing at least one location of the first failed micro-device on the carrier substrate; and

determining the location of the micro-device void on the receiving substrate according to the location of the first failed micro-device on the carrier substrate.

11. The method of claim 4, further comprising:

testing the micro-devices on the receiving substrate to determine if there is at least one second failed micro-device on the receiving substrate; and

repairing the second failed micro-device on the receiving substrate with at least one repairing micro-device.

12-20. (canceled)

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专利名称(译)	用于转移的中间结构，用于转移的微器件的制备方法，以及用于处理半导体器件阵列的方法		
公开(公告)号	US20170278760A1	公开(公告)日	2017-09-28
申请号	US15/080607	申请日	2016-03-25
[标]申请(专利权)人(译)	美科米尚技术有限公司		
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IPC分类号	H01L21/66		
CPC分类号	H01L22/14 H01L22/22 H01L21/67144 H01L21/67271 H01L21/6831 H01L21/6838 H01L25/0753		
其他公开文献	US9842782		
外部链接	Espacenet USPTO		

摘要(译)

一种用于制备多个用于转移的微器件的方法包括将微器件临时键合到载体衬底上;测试载体基板上的微器件，以确定微器件中是否存在至少一个第一个失效的微器件;从载体基板上移除第一个失效的微器件。

